

HUNTSVILLE OPERATIONS SUPPORT CENTER

presented by:

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HUNTSVILLE OPERATIONS SUPPORT CENTER (HOSC)

The HOSC is a multimission control and support facility designed to provide simultaneous support to several diverse missions, using a common set of processing equipment and facilities. The facility currently consists of:

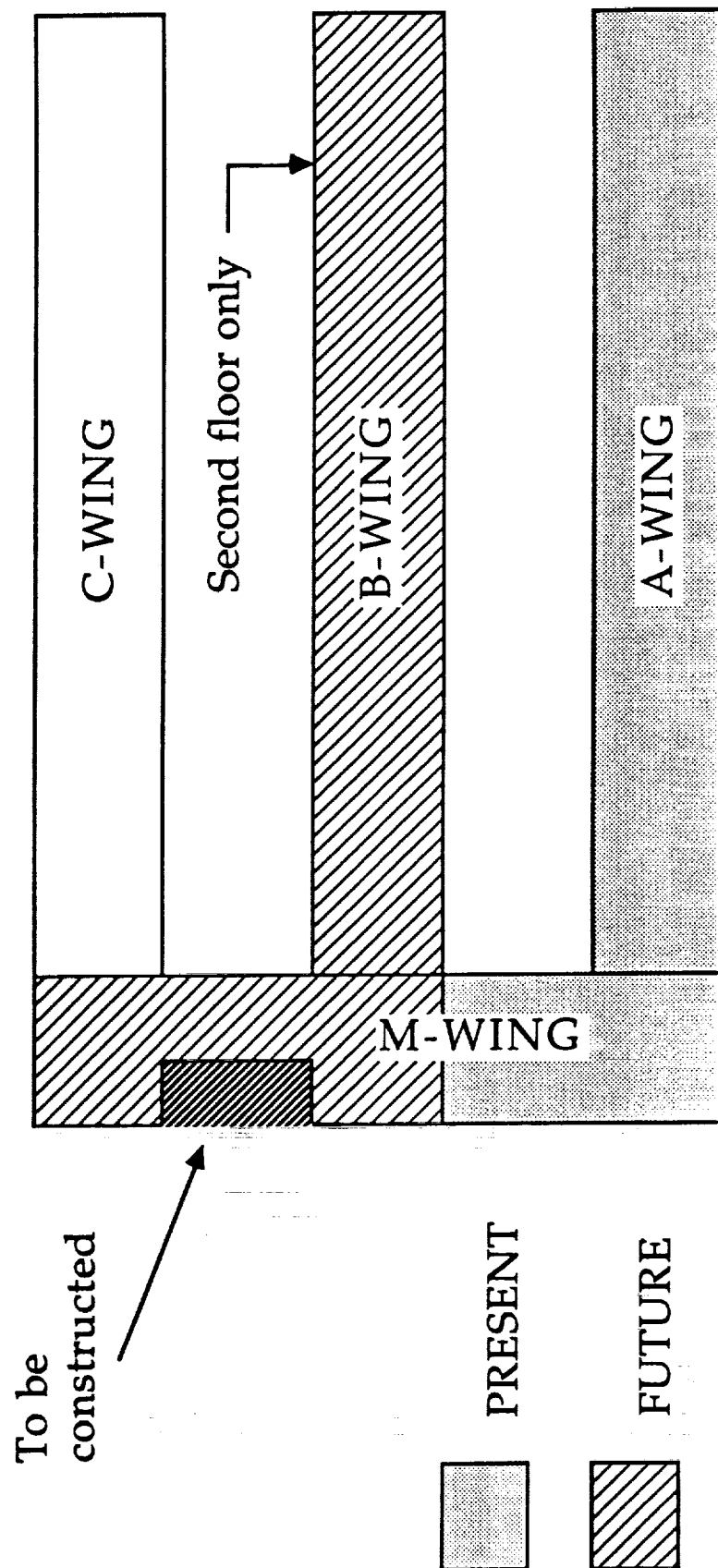
- Two payload control area "front rooms", with associated support areas
- 12 online conference work areas, with data, audio, and video services
- Two science operations areas, totalling 6000 sq. ft. of raised floor space
 - Data, audio, and video services; audio keysets can be configured to allow experimenters to converse directly with payload crew
 - Access to high-rate science data interfaces
- 9000 sq. ft. computer room with central configuration monitoring area
- Redundant power and A/C
 - Two power feeds from different areas of TVA grid, with automatic transfer
 - Battery and generator backup for all power except overhead lights
- Conference areas with audio teleconferencing capability
- Lab space for enhanced development

MISSIONS SUPPORTED BY THE HOSC:

- 1960s:
 - Saturn Launch Engineering Console Room
- 1970s:
 - Skylab Engineering Console Room
- 1980s:
 - Shuttle Engineering Console Room
 - Hubble Space Telescope Engineering Support Center (ESC)
 - Inertial Upper Stage (IUS) ESC
- Present:
 - Shuttle Engineering Console Room
 - Spacelab Payload Operations Control Center (POCC)
 - IUS ESC
 - Propulsion test stand support
- Late 1990s:
 - All of the present activities, plus:
 - Space Station Freedom Payload Operations Integration Center (POIC)
 - SSF Work Package 01 ESC
 - SSF OSSA Integrated Science Operations Center (ISOC)
 - Astronomical X-ray Astrophysics Facility (AXAF) POCC
 - AXAF ESC

THE HOSC FACILITY

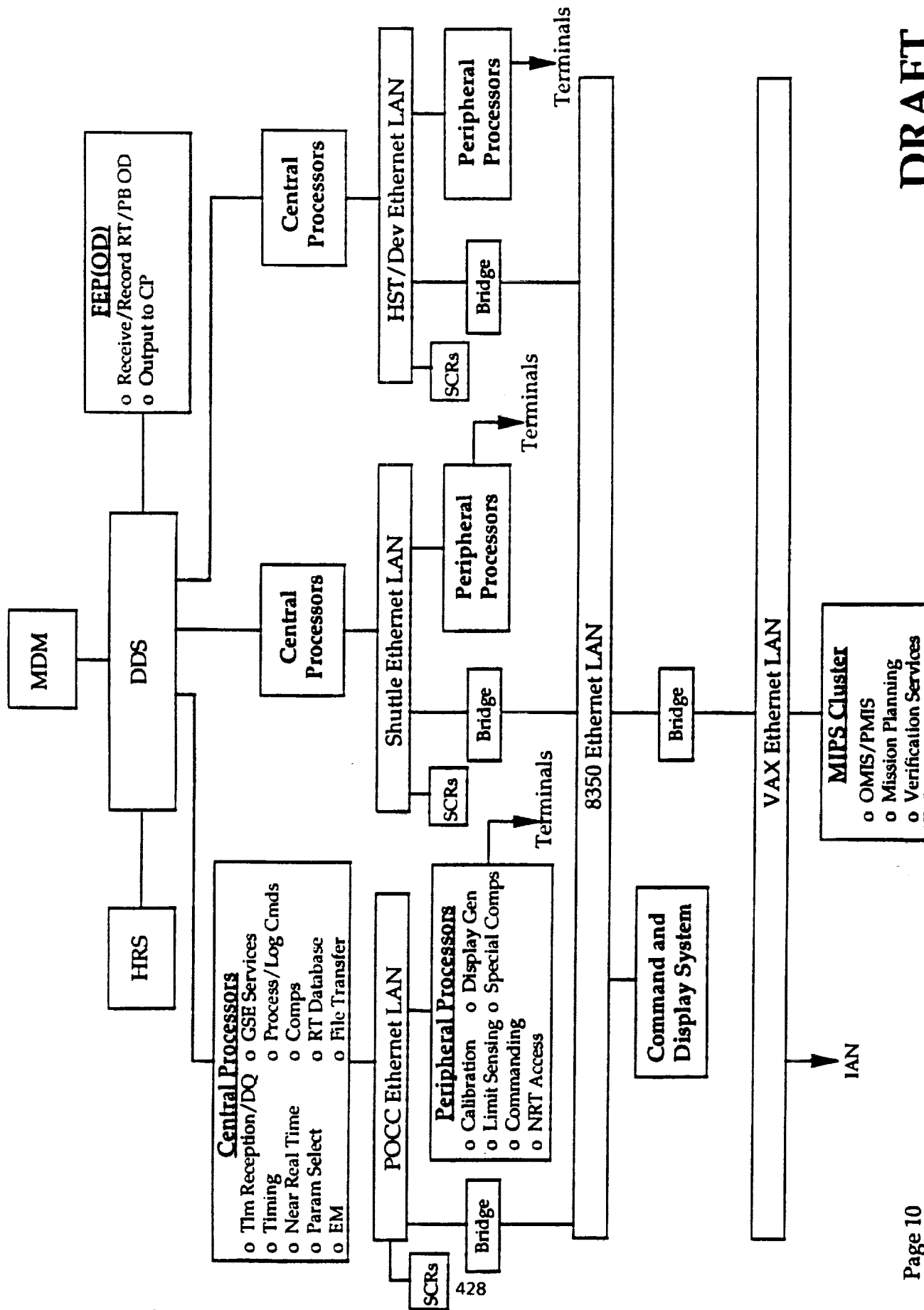
- Current facility occupies building 4663 A-wing and part of M-wing
- Future expansion to occupy upper floor of B-wing and remainder of M-wing



HOSC GENERIC SYSTEM GOALS

- To build and operate a generic system capable of multimission support
- To perform multiple mission supports simultaneously
- To be able to exchange components and share redundancy
- To build systems using COTS products when possible
- To allow for expansion and accommodation of new missions
- To use common data transfer protocols across projects, simplifying data exchange and eliminating need for protocol conversion

HOSC Existing Architecture



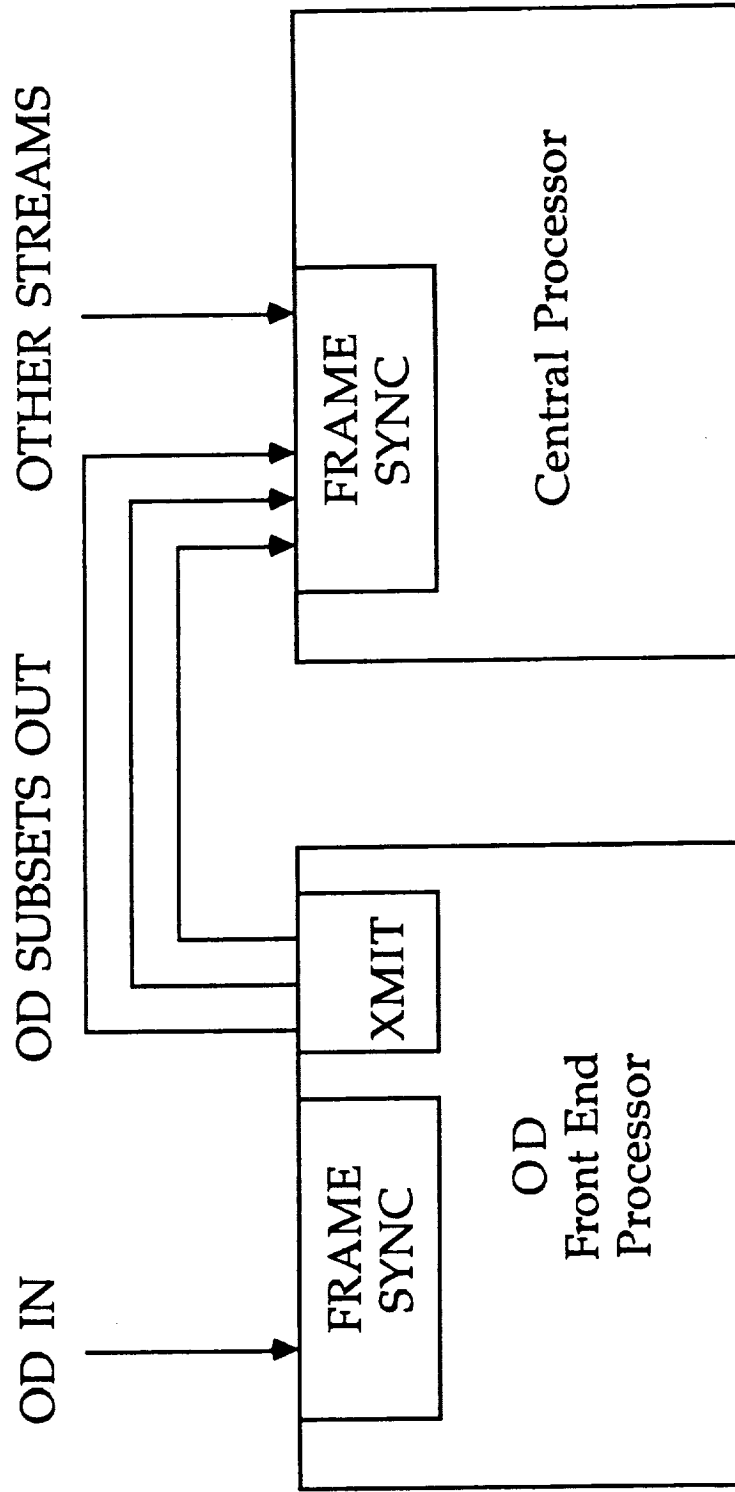
CURRENT HOSC MISSION REQUIREMENTS

- Shuttle Engineering Console Room:
 - process Orbiter Downlink (OD) - non-standard stream
 - process redundant Launch Processing System (LPS) data
 - process redundant Engine Instrumentation System (EIS) data
 - total data input rate ~ 1.3 Mb/sec
 - extensive exception monitoring (drives C&W lamps)
 - post-launch ops recorder dump processing at 1 Mb/sec
- Spacelab POCC:
 - process Orbiter Downlink
 - process Experiment Computer and Subsystem Computer I/O
 - process experiment dedicated channels at up to 2 Mb/sec
 - perform payload commanding
 - payload ops planning and timelining; orbit prediction
- IUS ESC
 - process Orbiter Downlink
 - process IUS subset data inserted into OD by payload data interleave
 - process data from ARIA aircraft or other sources

CURRENTLY EMPLOYED HARDWARE AND SOFTWARE

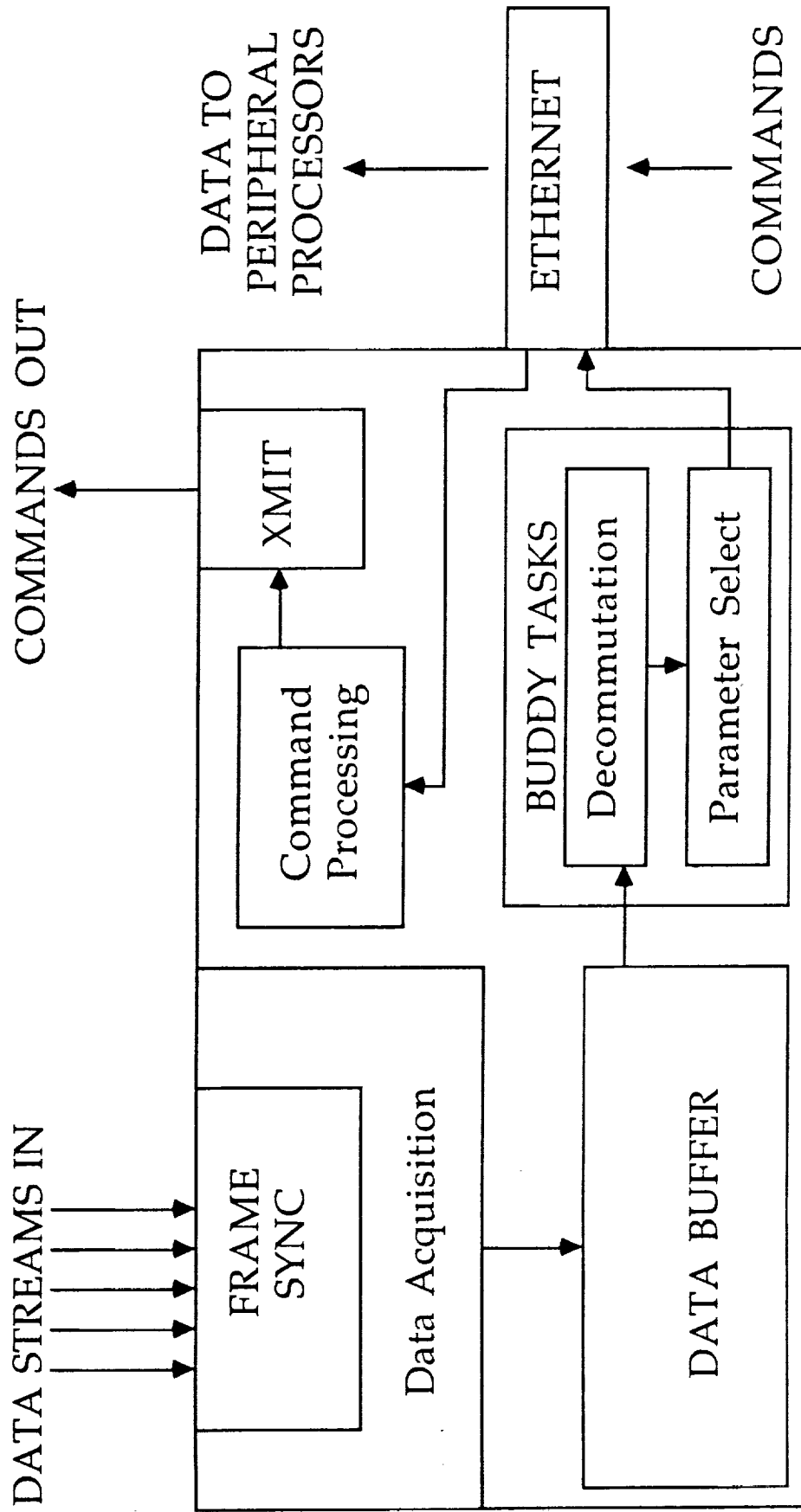
- Data switching — custom hardware
- Front-end processors and central processors:
Hardware — Concurrent 3200-series with custom telemetry interfaces
Software — assembly and Fortran, no COTS except OS and compilers
- Networking:
Layers 1 and 2 — COTS Ethernet products
Layers 3 and above — custom protocol, plus some DECnet
- Peripheral processors:
Hardware — DEC Microvax
Software — mostly Fortran, some DCL and assembly, little COTS
Displays — DEC VT200 and 300 series, Regis graphics, no GUI
- Mission planning and database systems — Vaxcluster, access from VT terminals via T-switches and terminal servers
- Communications: Electrospace digital audio, Image Video video matrix, dual 9" B&W and single 13" color NTSC monitors at each console

FRONT END PROCESSING



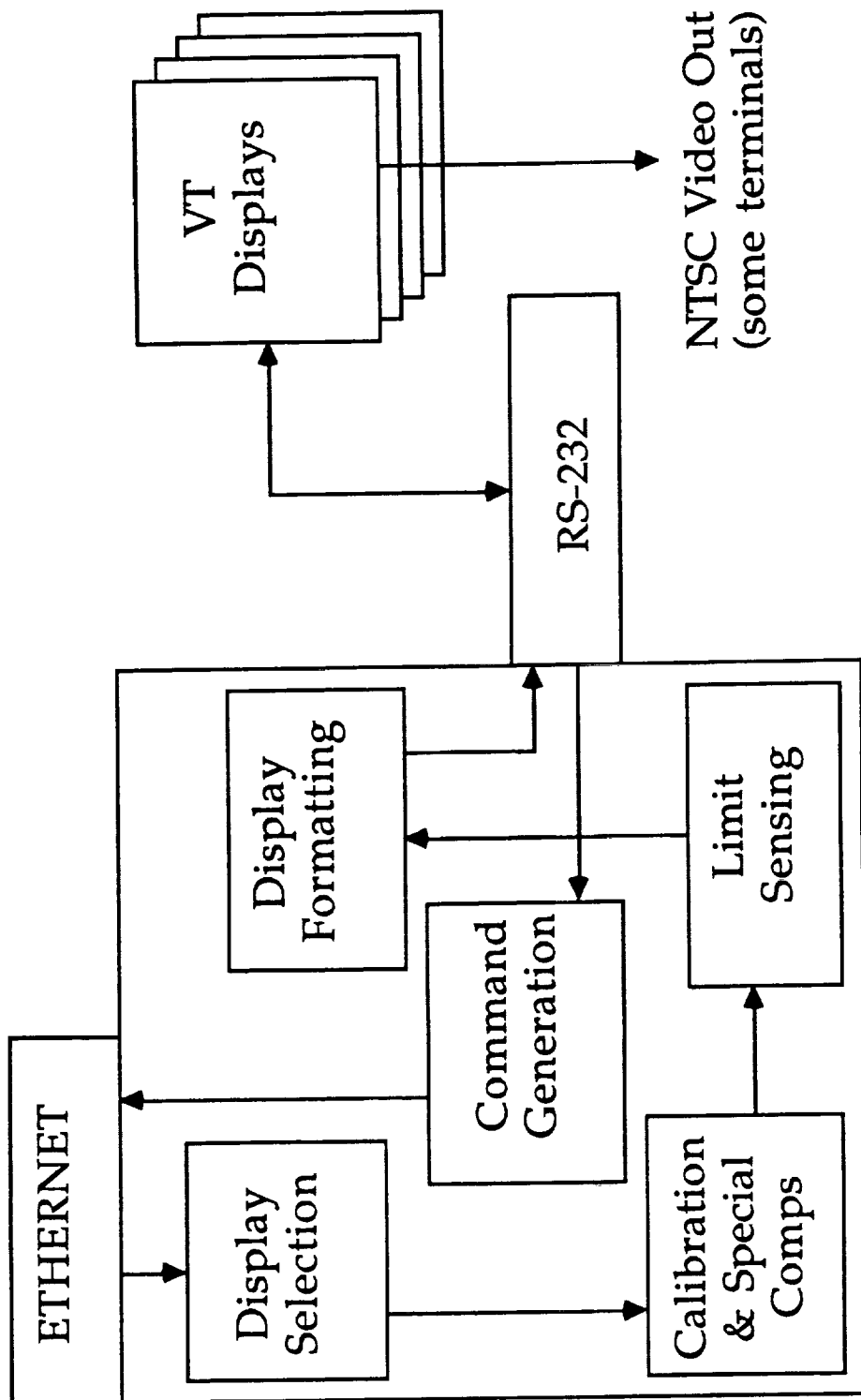
- OD Preprocessing performed by Front-End Processor
- All other acquisition and processing performed by Central Processor, with frame sync performed by custom input board

CENTRAL PROCESSING



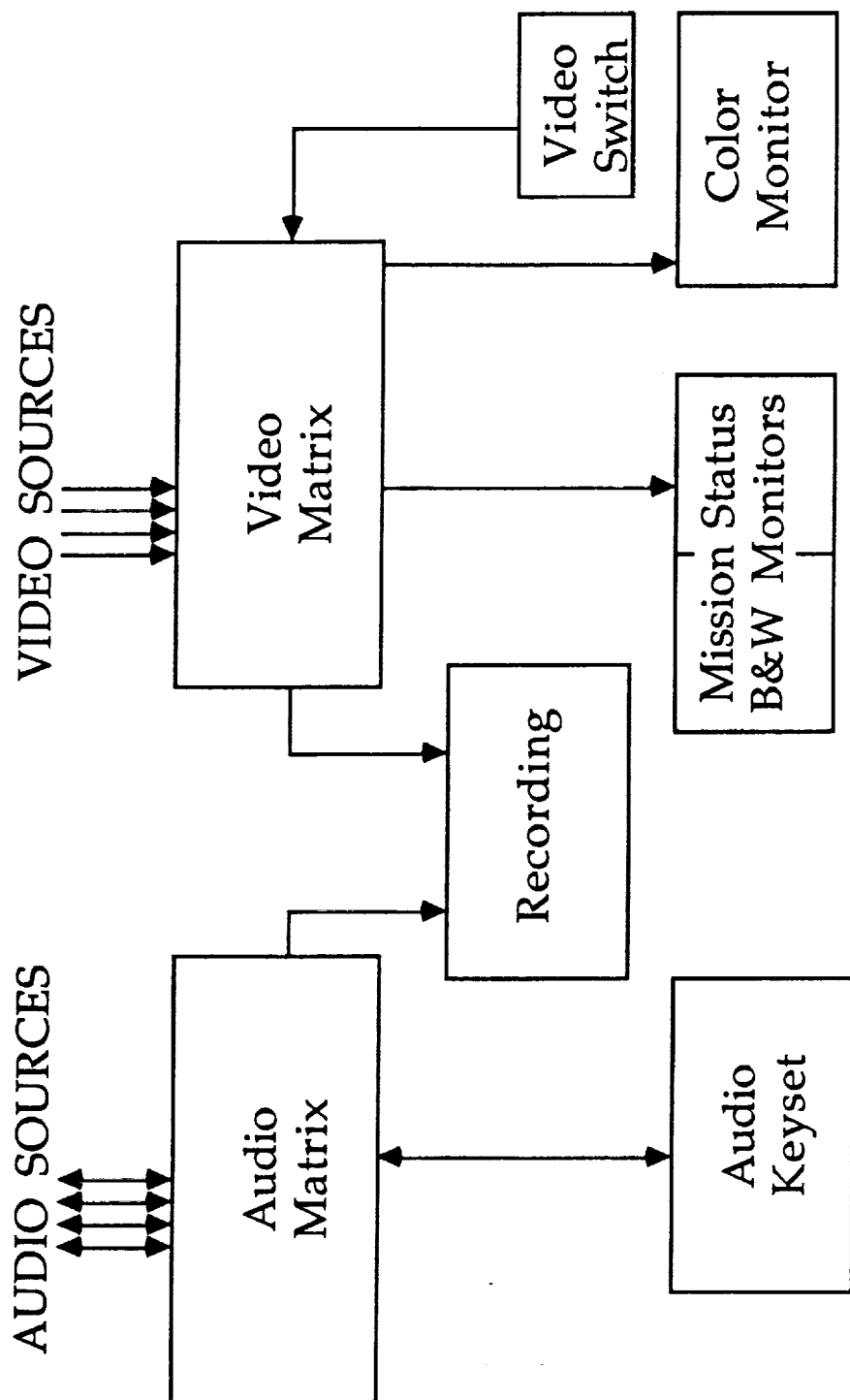
- Central processor performs triple-buffered acquisition, decommutation, and data selection, but not calibration (in most cases)
- CPs also perform command processing and system common services, including common use computations

PERIPHERAL PROCESSORS



- Peripheral Processors perform data calibration and formatting, sense limits and highlight limits exceeded, drive displays, and execute special comps
- Up to 4 displays per processor

COMMUNICATIONS



- Audio keysets provide 2-way internal and external audio, and access to telecom
— Remote keysets possible using fractional T1 circuits
- Video used primarily for display sharing and mission status

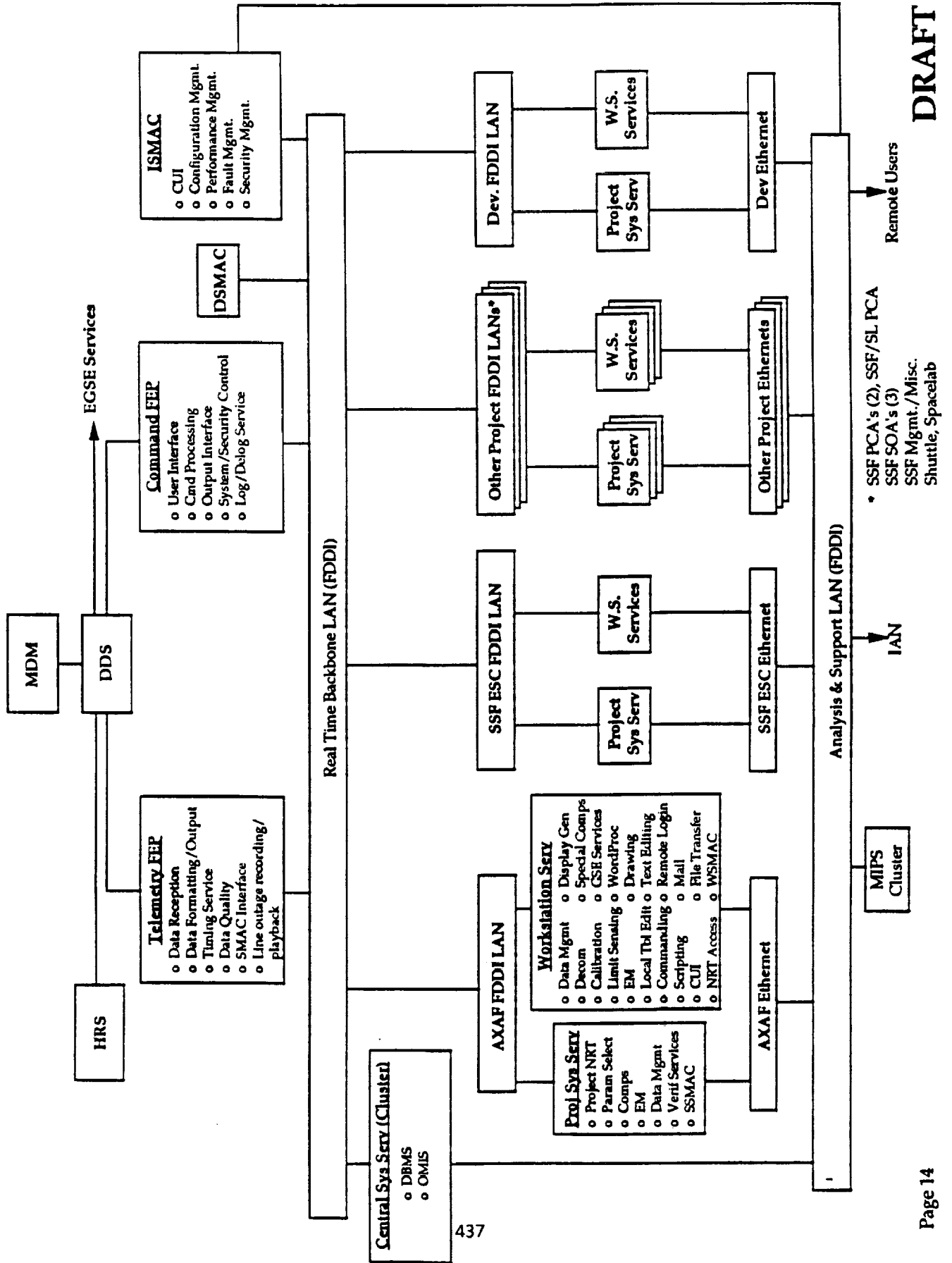
WHY ENHANCED DEVELOPMENT?

- Manpower-intensive systems result in rising operations costs
 - Personnel required for support is exponentially proportional to requirements
- Custom systems are difficult to maintain due to loss of knowledge via employee turnover
- Proprietary systems are expensive to upgrade; vendors eventually phase out support of obsolete systems
- Applications can't be maintained or easily ported to another platform
- Proliferation of network protocols for different applications
- Character-based dumb terminal interface, with minimal graphics
 - RS-232 interface severely limits graphics update ability
- Applications behave according to Parkinson's Law, but processing capabilities cannot easily be scaled up
- SSF and AXAF have requirements for 24-hour, 7-day, year-round support
 - Current system has some zero-fault-tolerant subsystems
- New interface requirements — NASCOM II, external users

ENHANCED DEVELOPMENT GOALS

- Upgrade hardware technology:
 - Distributed processing with COTS workstations and minicomputers
 - Higher-bandwidth, longer-distance networks with built-in redundancy
- Upgrade software technology:
 - Advanced programming languages (C, Ada, etc.)
 - POSIX-compliant operating systems and portable applications
 - GOSIP-compliant network protocols
 - Standards-based COTS products such as relational database and GUI
- Reduced training, operations, reconfiguration, and maintenance costs
- Meet SSF and AXAF requirements for 24-hour, 7-day, year-round support
- Support SSF and AXAF external users while improving system access controls and availability assurance
- Eliminate zero-fault-tolerant subsystems
- Accommodate new missions with minimum modifications
- *Maintain continuous support of ongoing missions during upgrade process*

HOSC Enhanced Architecture

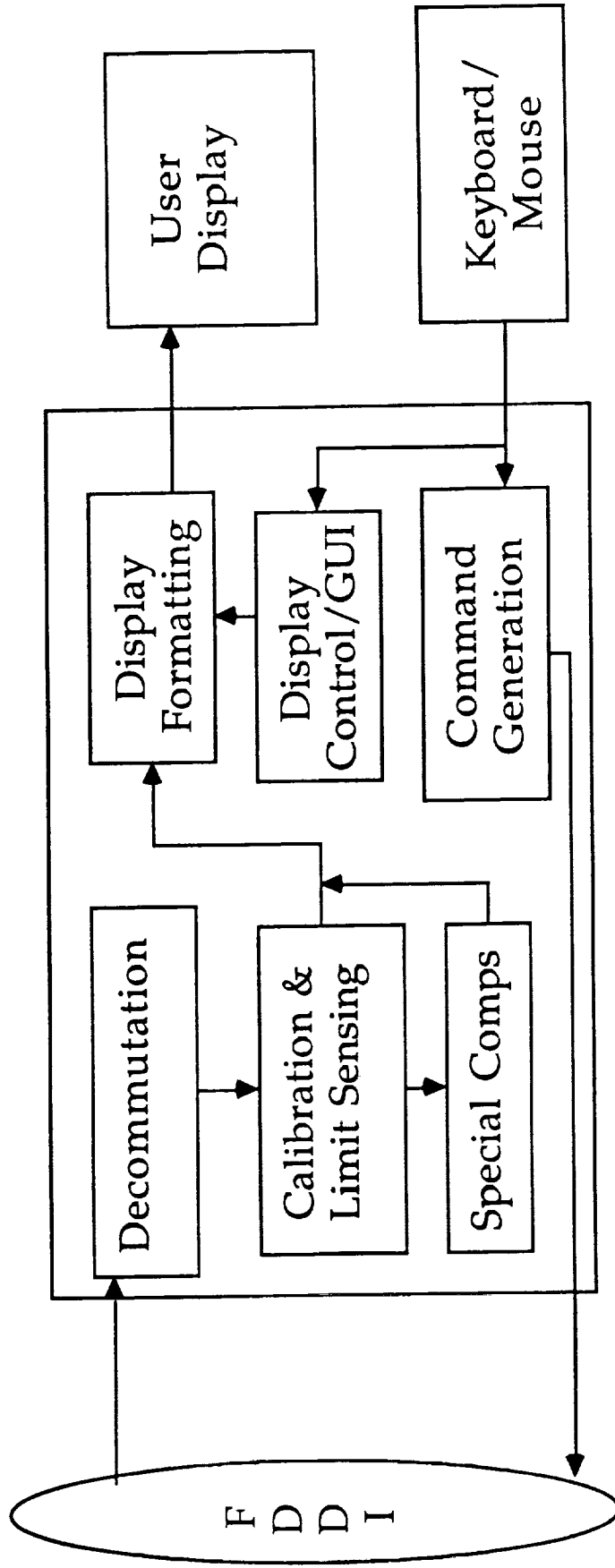


DRAFT

The diagram illustrates the Data Link Subsystem (DLS) architecture. It features a central processing block containing several functional modules. On the left, two external inputs are shown: 'COMMANDS' and 'TELEMETRY'. 'COMMANDS' is connected to the 'RS-422 INTERFACE' and the 'NASCOM II INTERFACE'. 'TELEMETRY' is connected to the 'RS-422 INTERFACE'. The 'RS-422 INTERFACE' and 'NASCOM II INTERFACE' both feed into a central bus. This bus connects to 'TDM Telemetry Acquisition' and 'CCSDS Telemetry Acquisition'. Both acquisition modules feed into 'Command Processing'. 'Command Processing' has bidirectional connections with 'Data Routing' and 'Frame Subsetting'. 'Data Routing' is connected to 'Packet Separation/Defragmenting'. Finally, 'Data Routing' outputs to an external 'FDDI' (Fiber Distributed Data Interface) network, represented by an oval at the top of the diagram.

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WORKSTATIONS



- Workstations process raw telemetry and extract needed data
- Display uses graphics user interface with menus, buttons, sliders, etc.
- Direct interface to project FDDI
- Alternate user input/output peripherals can be supported

SYSTEM SERVICES

System services machines will be attached to backbone net and to project nets for:

- Common use computations and mission status display generation
- Near-real-time data services
- Database and file services
- Project-specific commanding services
- Ground support equipment interface services
- Any other services requiring project-wide or system-wide access

INTEGRATED SYSTEM MONITOR AND CONTROL

Integrated system monitor and control consolidates status information and provides subsystem control in a centralized service with common display formats. Subsystems are:

- Data Acquisition and Distribution (FEPs, networks, NASCOM interfaces)
- System services processors
- Workstations
- Line outage recording and archiving
- External interfaces
- Facility (door monitoring, power, A/C, fire suppression)

ENHANCED DEVELOPMENT SCHEDULE

- Preliminary design review — summer 1992
- Critical design review — summer 1993
- Enhanced data system operational — fall 1995
- SSF ESC operations begin 3/96, POIC operations begin 6/96
- AXAF operations begin 10/97
- Existing missions and users to be migrated to enhanced system in 1995-1996 timeframe
- All previous architecture subsystems out of service by end of 1998